

— Design of Correct Circuits, Budapest 2008 —

Defining Elastic Circuits with Negative Delays

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Latency-Insensitive Design

- ✱ Implement a given functionality in a way that tolerates the latency changes of components and wires connecting them.
- ✱ Pioneering work: Carloni, McMillan, Sangiovanni-Vincentelli [CAV'99]
- ✱ Intel project **SELF** (Synchronous Elastic Flow)
 - Kishinevsky, Cortadella, ... [TAU'05, DAC'06, DAC'07]
- ✱ Theoretical foundation for simple SELF [FMCAD'06]
- ✱ This presentation: Challenge in extending the theory

The Idea of an Elastic Circuit

- ★ A behavior of an elastic inverter:



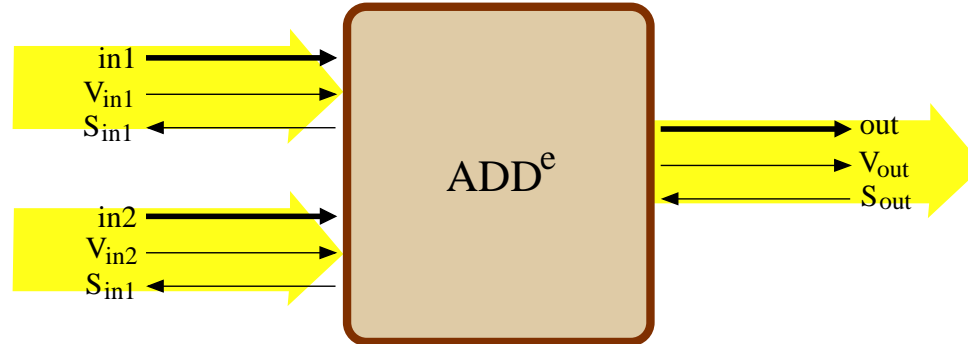
- data transfer does not occur at every cycle
- tokens and bubbles

- ★ Why bubbles?

- valid **input** not there, or INV cannot take it
- **output** not yet computed, or the consumer not ready to take it

Elastic Control

- Transfer along a wire X occurs when both parties are ready
 - Producer ready: the **valid bit** V_X is 1
 - Consumer ready: the **stop bit** S_X is 0
 - **elastic channels**: wire triples $\langle X, V_X, S_X \rangle$



- Transfer and token count on a channel:

cycle	0	1	2	3	4	5	6	7	8	9	...
X	*	<i>A</i>	<i>B</i>	<i>B</i>	<i>B</i>	<i>C</i>	*	*	<i>D</i>	<i>D</i>	...
V_X	0	1	1	1	1	1	0	0	1	1	...
S_X	0	0	1	1	0	0	0	1	1	0	...
tct_X	0	1	1	1	2	3	3	3	3	4	...

Correctness: Persistence

✱ If you're ready for handshake, you stay ready till it happens

- $\Box (V_Y \wedge S_Y \Rightarrow (V_Y)^+)$ for every output Y
- $\Box (\neg V_X \wedge \neg S_X \Rightarrow (\neg S_X)^+)$ for every input X

Correctness: Data

- ✱ Every elastic circuit E is tied to a reference system R
 - E is an **elasticization** of R
- ✱ Require: **if you take any behavior of E and ignore the bubbles, the result is a behavior of R**
 - We need to be more precise if we want this property to be proved or model-checked

Correctness: Liveness

- Need a condition strong enough to **guarantee infinite flow of tokens on all channels** assuming a cooperating environment



- Weak fairness:

- $\square (\square en_out_Y \rightarrow \diamond V_Y)$ for every output Y
- $\square (\square en_in_X \rightarrow \diamond \neg S_X)$ for every input X

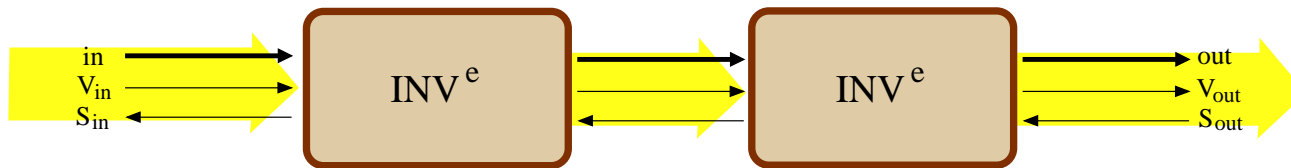
where

- $en_out_Y = (tct_Y - tct_X > 0)$ (there is a token inside)
- $en_in_X = (tct_Y - tct_X < C)$ (capacity C not reached)

- What if there are more than two wires? [Will return to this]

The Composition Theorem: An Instance

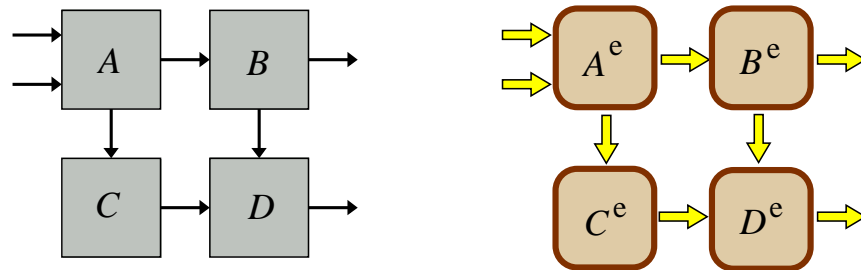
- Two elastic inverters of capacities C_1 and C_2 can make an elastic buffer of capacity $C_1 + C_2$.



- We can check that the combined circuit has the required correctness properties.

General Composition Theorem (Desired)

¿Theorem? Suppose the reference system R is obtained from subsystems R_1, \dots, R_n by joining wires. Suppose also that R_1^e, \dots, R_n^e are elasticizations of these subsystems. Then if we join the channels of the circuits R_i^e following the same pattern in which R is obtained from the R_i , the resulting circuit will be an elasticization of R .



- ★ Proved in [FMCAD'06] for a restricted class of reference systems and a restricted definition of elastic circuits.

Extended Theory Needed

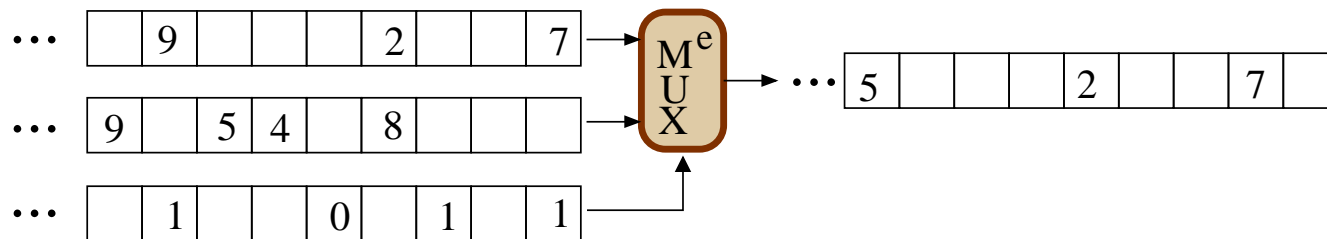
- ★ Reference systems need not be circuits



- Token count inside can be negative

- ★ Early evaluation

[Cortadella&Kishinevsky, DAC'07]

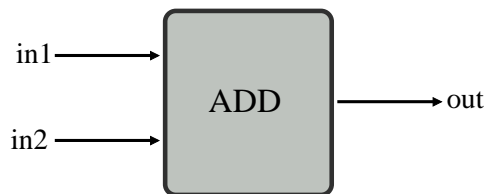


- Output tokens produced without waiting for irrelevant input tokens
- Token count on a channel can be negative (“anti-tokens”)

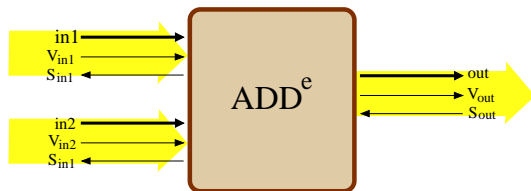
Systems Modeled as Stream Transformers

Definition Given a set of **wires** W , a **W -system** is a set of **behaviors**, where a behavior is a W -indexed records of streams.

Definition In a **functional system**, $W = I + O$, and output streams depend functionally on the inputs. $(F: \llbracket I \rrbracket \rightarrow \llbracket O \rrbracket)$



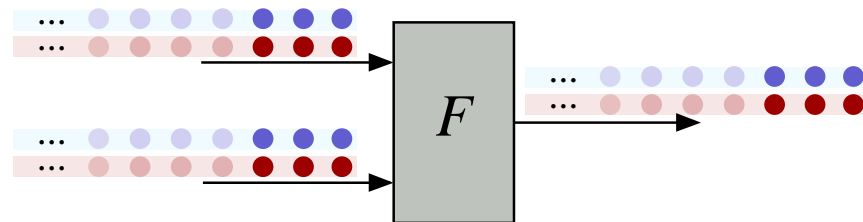
- $W = \{\text{in1}, \text{in2}, \text{out}\}$, $I = \{\text{in1}, \text{in2}\}$, $O = \{\text{out}\}$
- Behaviors: $\sigma = \langle \sigma.\text{in1}, \sigma.\text{in2}, \sigma.\text{out} \rangle$ where
 $(\forall i = 0, 1, \dots) (\sigma.\text{out}[i] = \sigma.\text{in1}[i] + \sigma.\text{in2}[i])$
- Ex: $\sigma.\text{in1} = \langle 2, 2, 2, \dots \rangle$ $\sigma.\text{in2} = \langle 1, 2, 3, \dots \rangle$
 $\sigma.\text{out} = \langle 3, 4, 5, \dots \rangle$



- $W = \{\text{in1}, \text{in2}, \text{out}, V_{\text{in1}}, V_{\text{in2}}, V_{\text{out}}, S_{\text{in1}}, S_{\text{in2}}, S_{\text{out}}\}$
- Behaviors: ... (nine streams in each)

Causal Systems (Circuits Abstractly)

Outputs at the first k cycles are determined by inputs at the first k cycles.



Definition A **causal system** is given by a function $F: \llbracket I \rrbracket \rightarrow \llbracket O \rrbracket$ satisfying the property

$$\left(\begin{array}{l} \forall k \geq 0 \\ \forall Y \in O \\ \forall \sigma, \sigma' \in \llbracket I \rrbracket \end{array} \right) \bigwedge_{X \in I} \sigma.X \sim_k \sigma'.X \implies F(\sigma).Y \sim_k F(\sigma').Y$$

- **Definition** $a \sim_n b$ iff $\text{prefix}(n, a) = \text{prefix}(n, b)$
- **Example:** $a = \langle 1, 2, 3, 4, 5, \dots \rangle$ $b = \langle 1, 2, 7, 4, 5, \dots \rangle$
 $\therefore a \sim_2 b$ $\therefore a \not\sim_3 b$

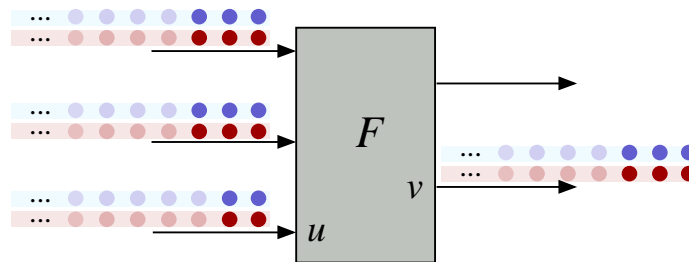
Sequential Dependency

★ Feedback: When is it a causal system too?



Definition An input-output pair (u, v) is **sequential** if

$$\left(\begin{array}{l} \forall \sigma, \sigma' \in \llbracket I \rrbracket \\ \forall k \geq 0 \end{array} \right) \begin{array}{l} \sigma.u \sim_{k-1} \sigma'.u \\ \wedge \\ (\forall x \neq u) \sigma.x \sim_k \sigma'.x \end{array} \implies F(\sigma).v \sim_k F(\sigma').v$$



Feedback Lemma If (u, v) is sequential, then the feedback system is causal.

Systems with Specified Delays

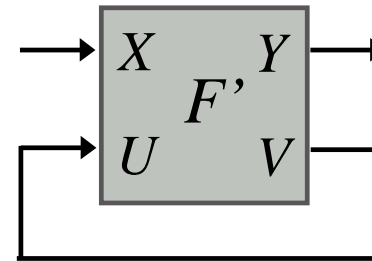
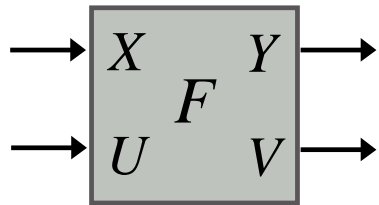
Give an integer δ_{XY} for each input-output pair X, Y ; let $\delta = \|\delta_{XY}\|$.

Definition A δ -system:

$$\left(\begin{array}{l} \forall k \geq 0 \\ \forall Y \in O \\ \forall \sigma, \sigma' \in \llbracket I \rrbracket \end{array} \right) \bigwedge_{X \in I} \sigma.X \sim_{k-\delta_{XY}} \sigma'.X \implies F(\sigma).Y \sim_k F(\sigma').Y$$

- * δ_{XY} “is” the initial number of tokens between X and Y
- * We saw a negative δ_{XY} in the TAIL system

The Feedback Theorem for δ -systems



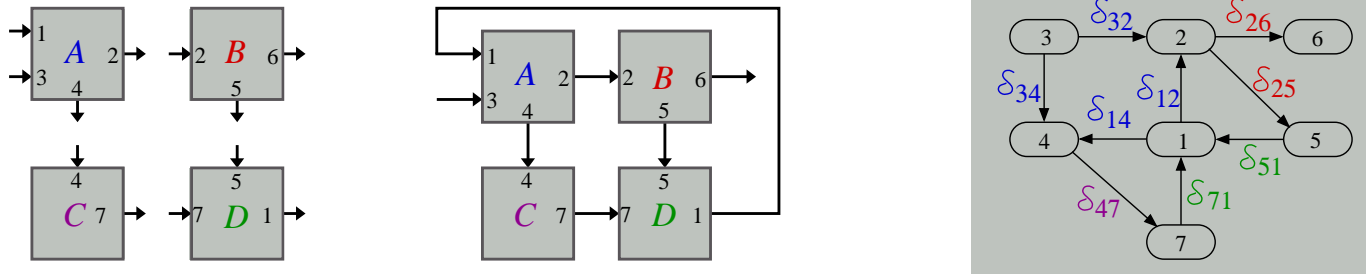
Theorem Suppose F is a δ -system and $\delta_{UV} > 0$. Then F' is a δ' -system, where

$$\delta'_{XY} = \min(\delta_{XY}, \delta_{XV} + \delta_{UY})$$

for every input-output pair X, Y .

The Cycle Sum Test

[Wadge, 1979]



Given a network of δ -systems, draw the graph whose nodes are the wires in the system, and the edges are the input-output pairs of all component systems, each labeled with its delay number.

Theorem If the sum of labels along any closed path is positive, then the network is a legitimate δ -system.

- Improves the combinational loop theorem
- The original Wadge's result is about Kahn networks
- Similar result by Gay&Natarajan (2003) in a categorical model of networks (with positive δ 's)

Back To Modeling Elasticity: Token Counts

★ Liveness conditions

$$\boxed{\square (\square \text{en_out}_Y \rightarrow \diamond V_Y)}$$

$$\boxed{\square (\square \text{en_in}_X \rightarrow \diamond \neg S_X)}$$

★ The enabling predicates? —For the inverter we had

- $\text{en_out}_Y = (\text{tct}_Y - \text{tct}_X > 0)$ (there is a token inside)
- $\text{en_in}_X = (\text{tct}_Y - \text{tct}_X < C)$ (capacity C not reached)

★ New notation:

- δ_{XY} = the initial number of tokens between X and Y
- tct_{XY} = the current number of tokens between X and Y

$$\therefore \text{Basic equation: } \text{tct}_X + \delta_{XY} = \text{tct}_Y + \text{tct}_{XY}$$

$$\therefore \text{en_out}_Y \text{ must be at least as strong as } (\forall X \in I)(\text{tct}_{XY} > 0)$$

The Capacities and Bubble Counts

★ There must be a maximum C_{XY} of the number of tokens between X and Y .

★ New notation:

- β_{YX} = the initial amount of free space between X and Y
- bct_{YX} = the current number of free space between X and Y

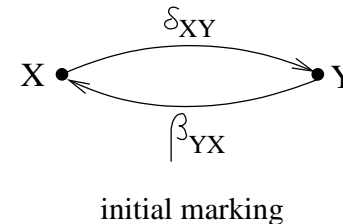
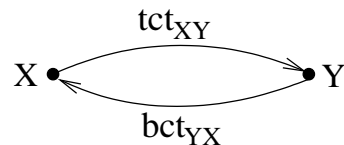
∴ Basic equation: $tct_Y + \beta_{YX} = tct_X + bct_{YX}$

∴ Also: $tct_{XY} + bct_{YX} = \delta_{XY} + \beta_{YX} = C_{XY}$

∴ en_in_X must be at least as strong as $(\forall Y \in O)(bct_{YX} > 0)$

The Associated Marked Graph

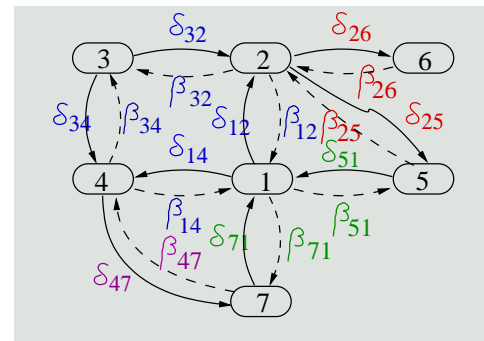
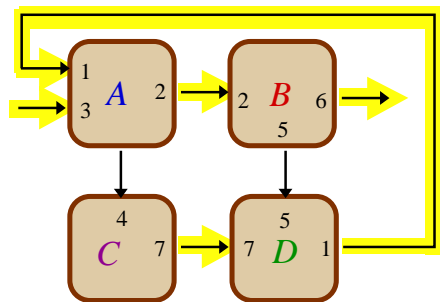
- ★ Elastic systems should be parametrized by matrices $\delta = \|\delta_{XY}\|$ and $\beta = \|\beta_{YX}\|$
- ★ Marked graph: Vertices are wires and a pair of edges joins every input with every output, labeled by token/bubble counts



- ★ Condition on (δ, β) : No non-positive cycles in the initial marking

Composition Theorem (Reformulated)

Theorem? Suppose a network E is built by joining channels of elastic systems E_1, \dots, E_n . (Each E_i is (δ_i, β_i) -elastic.) If the Wadge graph that includes all input-output and output-input edges passes the cycle sum test, then E is an elastic system.



- ★ Special case: $n = 1$, and E is obtained from E_1 by a single feedback
 - Sufficient to prove the general case

We Can't Prove It

★ Liveness conditions for E_1, \dots, E_n should imply the same conditions for E

★ The minimal enabling conditions

- $\text{en_out}_Y = (\forall X \in I)(\text{tct}_{XY} > 0)$

- $\text{en_in}_X = (\forall Y \in O)(\text{bct}_{YX} > 0)$

guarantee that at least one channel is always enabled

★ Stronger condition for outputs

- $\text{en_out}_Y = (\forall X \in I)(\text{tct}_{XY} > 0) \wedge (\forall Y' \in O)(\text{tct}_{Y'} \leq \text{tct}_Y)$

works if the matrix δ is positive

👉 Help develop the theory of elastic circuits!